

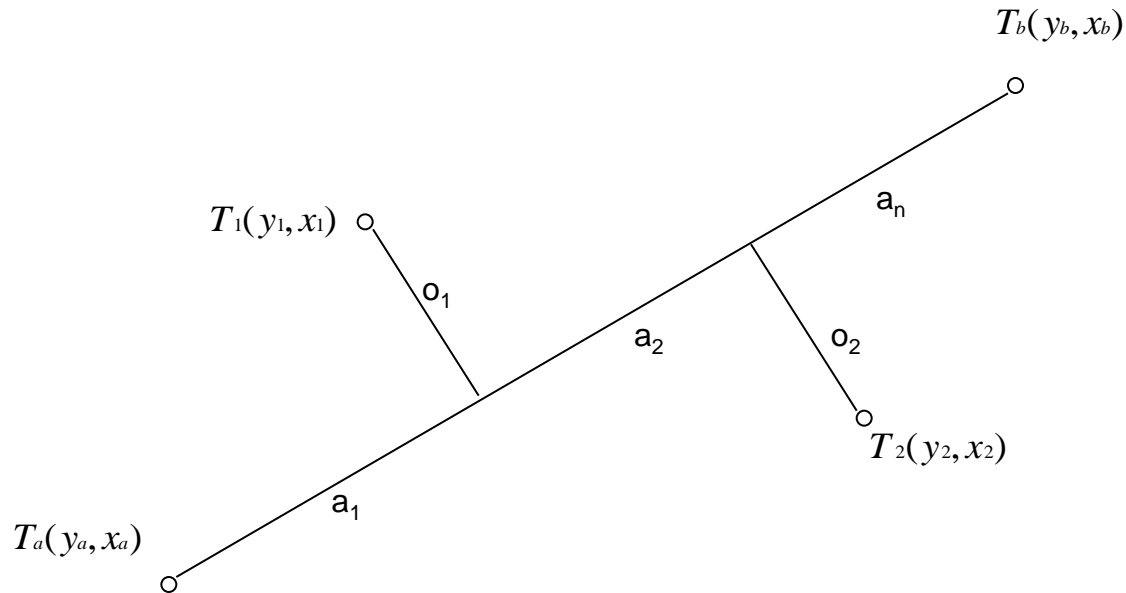
Male točke na okomici

Tomislav Sliepčević

Male točke na okomici

Mala točka po svom položaju može biti postavljena na ordinati koja je okomita na liniju snimanja.

Ta mala točka bit će definirana kao **mala točka na okomici**.



Položaj male točke bit će definiran svojim mjerenim relativnim koordinatama.

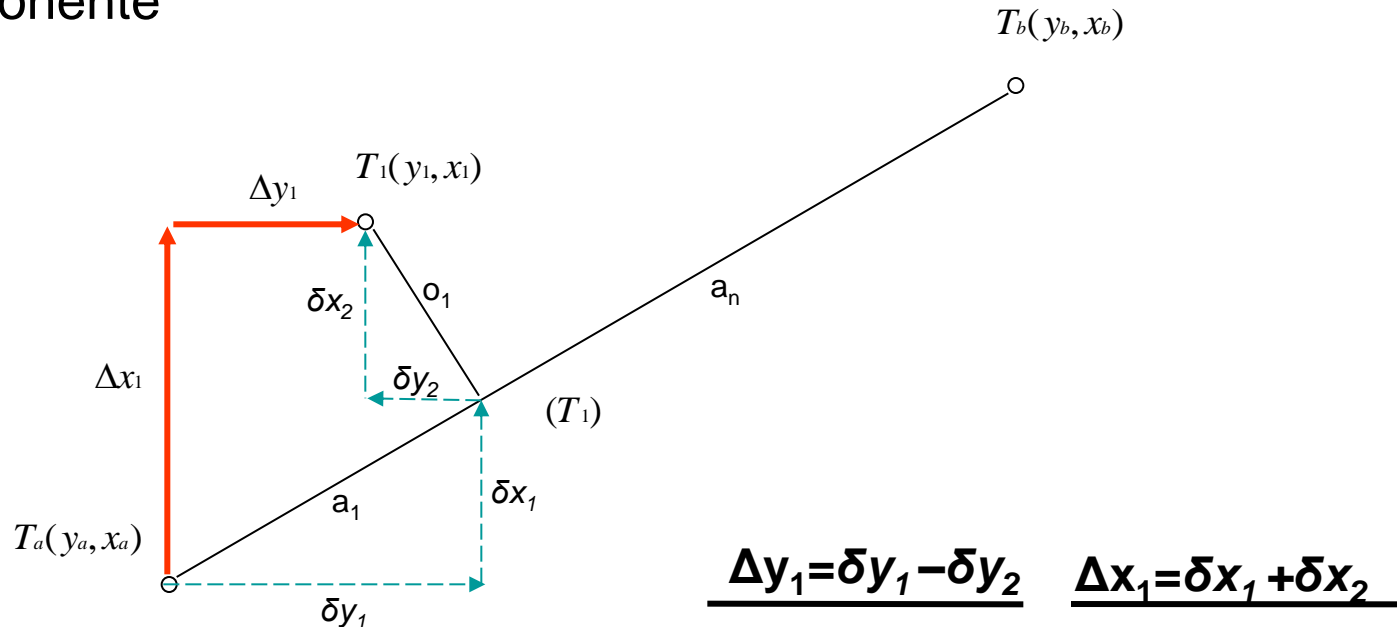
Relativne koordinate male točke na okomici su apscise a_i , i ordinate o_i .

Male točke na okomici

Male točke na okomici mogu s obzirom na liniju $T_a T_b$ biti na lijevoj ili desnoj strani od smjera snimanja i računanja.

a) Mala točka s lijeve strane od smjera računanja

- (T_1) nožište male točke na okomici = mala točka na liniji
- Koordinatne razlike Δy_1 i Δx_1 mogu se izraziti s dvije komponente



Male točke na okomici

Računanje komponentata koordinatnih razlika :

$$\delta y_1 : a_1 = (y_b - y_a) : [a] \Rightarrow \delta y_1 = \frac{(y_b - y_a)}{[a]} \cdot a_1$$

$$\delta x_1 : a_1 = (x_b - x_a) : [a] \Rightarrow \delta x_1 = \frac{(x_b - x_a)}{[a]} \cdot a_1$$

$$\delta y_2 : o_1 = (x_b - x_a) : [a] \Rightarrow \delta y_2 = \frac{(x_b - x_a)}{[a]} \cdot o_1$$

$$\delta x_2 : o_1 = (y_b - y_a) : [a] \Rightarrow \delta x_2 = \frac{(y_b - y_a)}{[a]} \cdot o_1$$

$$\sin \nu = \frac{y_b - y_a}{[a]} = p$$

$$\cos \nu = \frac{x_b - x_a}{[a]} = q$$

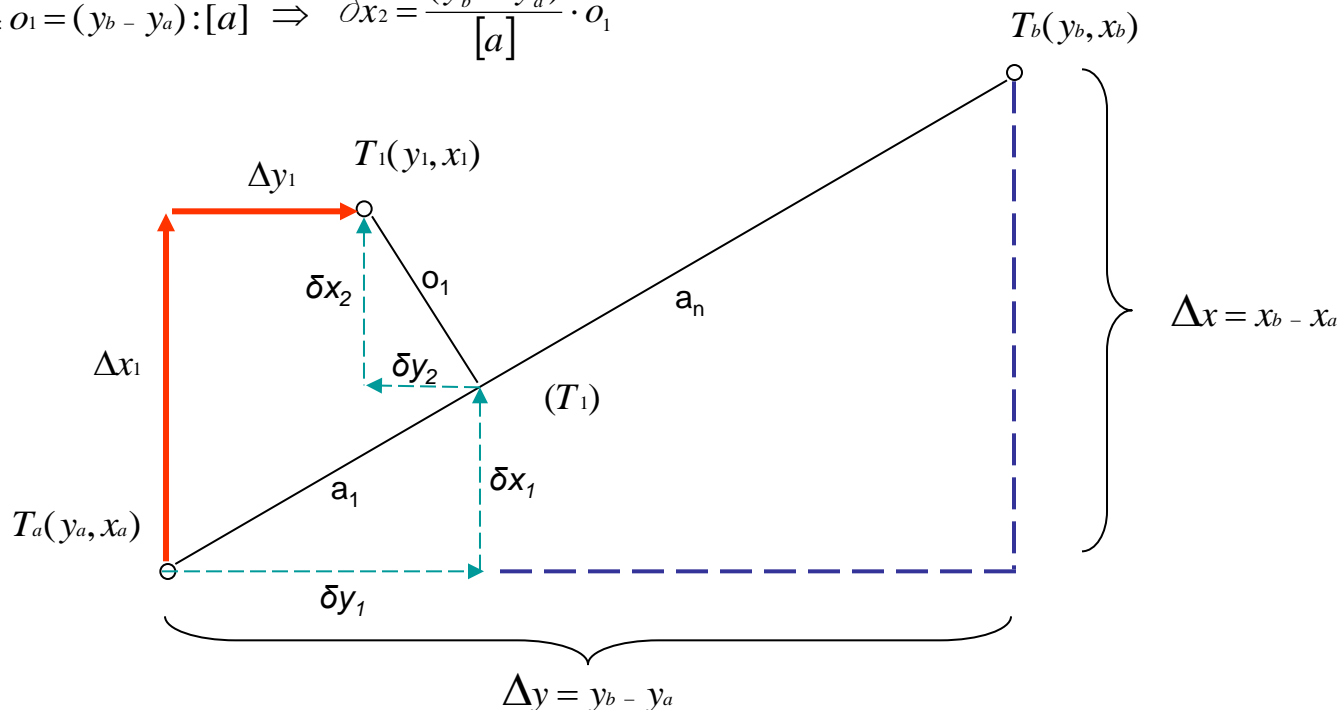
$$\delta y_1 = p \cdot a_1$$

$$\delta x_1 = q \cdot a_1$$

$$\delta y_2 = q \cdot o_1$$

$$\delta x_2 = p \cdot o_1$$

Koord.razlike
male točke –
nožišta na liniji



$$\underline{\Delta y_1 = \delta y_1 - \delta y_2 = p \cdot a_1 - q \cdot o_1}$$

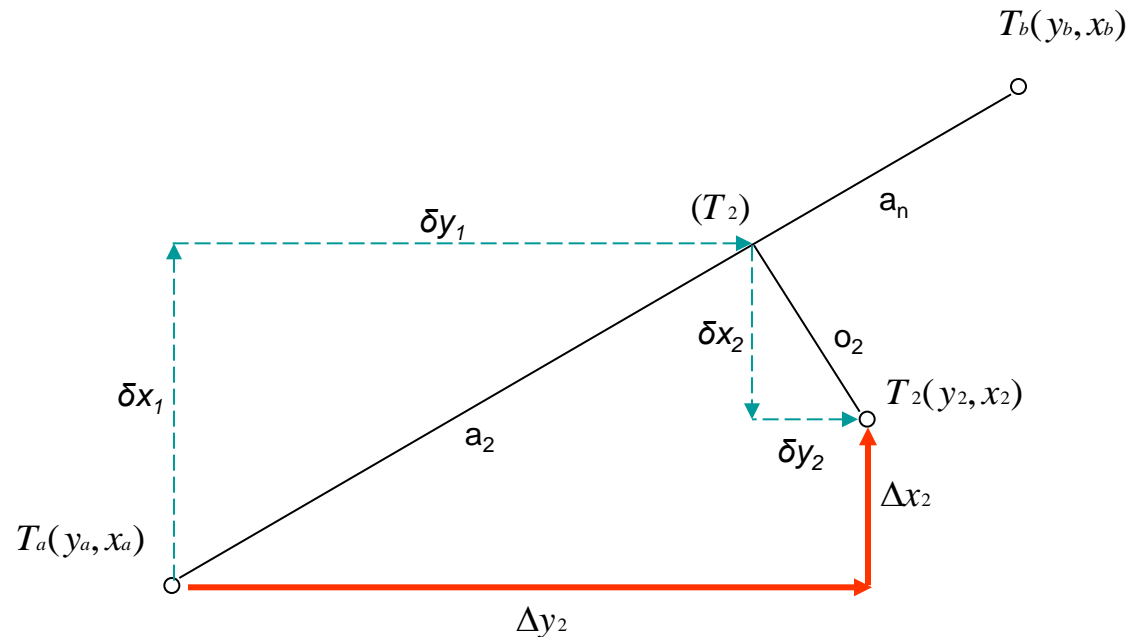
$$\underline{\Delta x_1 = \delta x_1 + \delta x_2 = q \cdot a_1 + p \cdot o_1}$$

Male točke na okomici

Male točke na okomici mogu s obzirom na liniju $T_a T_b$ biti na lijevoj ili desnoj strani od smjera snimanja i računanja.

b) Mala točka s desne strane od smjera računanja

- (T_2) nožište male točke na okomici = mala točka na liniji
- Koordinatne razlike Δy_2 i Δx_2 mogu se izraziti s dvije komponente



$$\underline{\Delta y_2 = \delta y_1 + \delta y_2}$$

$$\underline{\Delta x_2 = \delta x_1 - \delta x_2}$$

Male točke na okomici

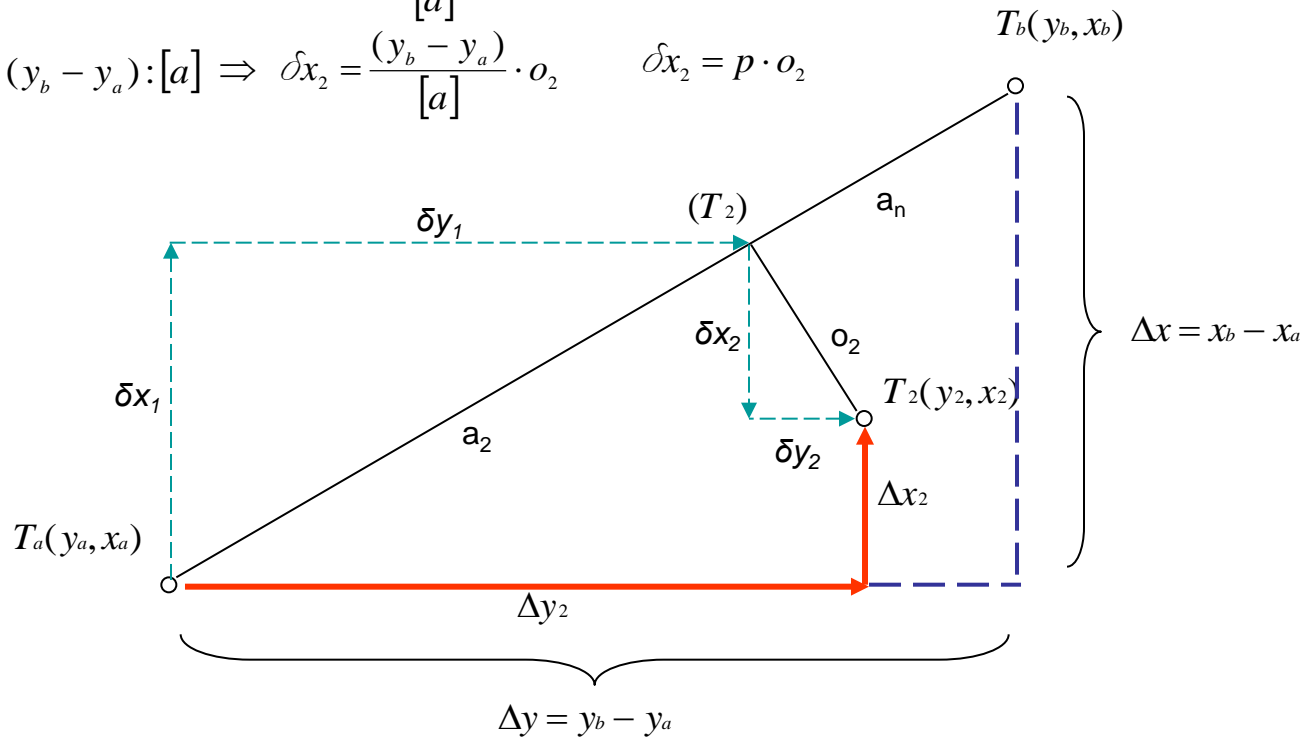
Računanje komponenta koordinatnih razlika :

$$\delta y_1 : a_2 = (y_b - y_a) : [a] \Rightarrow \delta y_1 = \frac{(y_b - y_a)}{[a]} \cdot a_2 \quad \delta y_1 = p \cdot a_2$$

$$\delta x_1 : a_2 = (x_b - x_a) : [a] \Rightarrow \delta x_1 = \frac{(x_b - x_a)}{[a]} \cdot a_2 \quad \delta x_1 = q \cdot a_2$$

$$\delta y_2 : o_2 = (x_b - x_a) : [a] \Rightarrow \delta y_2 = \frac{(x_b - x_a)}{[a]} \cdot o_2 \quad \delta y_2 = q \cdot o_2$$

$$\delta x_2 : o_2 = (y_b - y_a) : [a] \Rightarrow \delta x_2 = \frac{(y_b - y_a)}{[a]} \cdot o_2 \quad \delta x_2 = p \cdot o_2$$



$$\underline{\Delta y_2 = \delta y_1 + \delta y_2 = p \cdot a_2 + q \cdot o_2}$$

$$\underline{\Delta x_2 = \delta x_1 - \delta x_2 = q \cdot a_2 - p \cdot o_2}$$

Male točke na okomici

Male točke s lijeve strane

$$\Delta y_1 = p \cdot a_1 - q \cdot o_1$$

$$\Delta x_1 = q \cdot a_1 + p \cdot o_1$$

Male točke s desne strane

$$\Delta y_2 = p \cdot a_2 + q \cdot o_2$$

$$\Delta x_2 = q \cdot a_2 - p \cdot o_2$$

Univerzalni izrazi

$$\Delta y_i = p \cdot a_i + q \cdot o_i$$

$i = 1, 2, \dots, n$

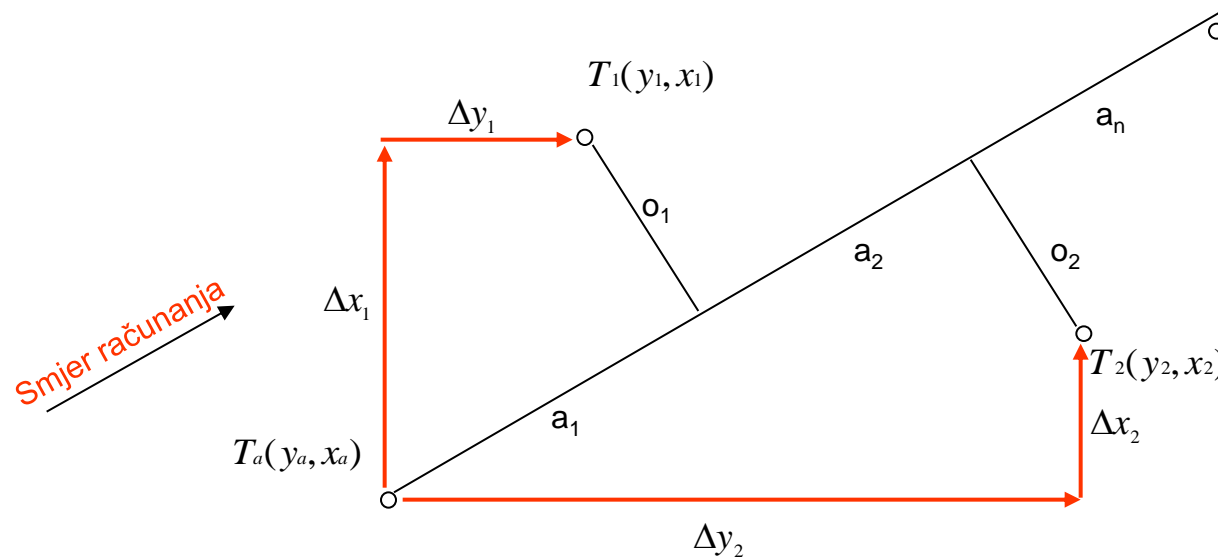
$$\Delta x_i = q \cdot a_i - p \cdot o_i$$

$i = 1, 2, \dots, n$

$T_b(y_b, x_b)$

Napomena:

Ako je točka s lijeve strane ordinata će dobiti negativni predznak



Definitivne koordinate malih točaka na okomici : $y_i = y_a + \Delta y_i$ $x_i = x_a + \Delta x_i$

Male točke na okomici

Nožišta malih točaka na okomici su ujedno i male točke na liniji : (T_1) ; (T_2)

$$(\Delta y_1) = a_1 \cdot \sin \nu_a^b$$

$$(\Delta y_2) = o_1 \cdot \sin \nu_{(1)}^1 = o_1 \cdot \sin(270^\circ + \nu_a^b) = -o_1 \cdot \cos \nu_a^b$$

$$\Delta y_1 = a_1 \cdot \sin \nu_a^b - o_1 \cdot \cos \nu_a^b$$

$$\Delta y_1 = p \cdot a_1 - q \cdot o_1$$

$$\underline{y_1 = y_a + \Delta y_1}$$

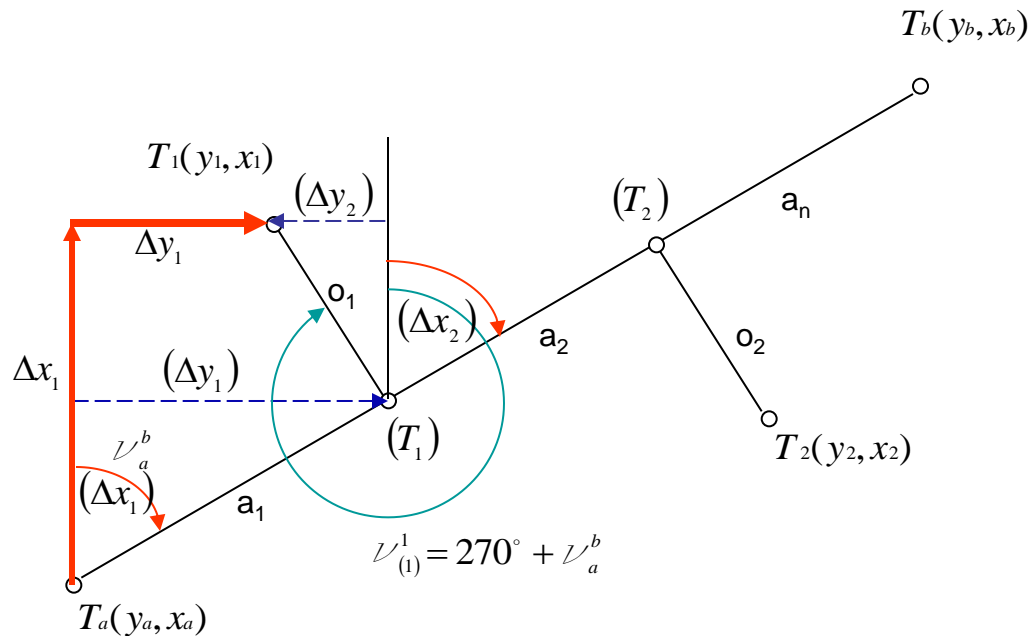
$$(\Delta x_1) = a_1 \cdot \cos \nu_a^b$$

$$(\Delta x_2) = o_1 \cdot \cos \nu_{(1)}^1 = o_1 \cdot \cos(270^\circ + \nu_a^b) = o_1 \cdot \sin \nu_a^b$$

$$\Delta x_1 = a_1 \cdot \cos \nu_a^b + o_1 \cdot \sin \nu_a^b$$

$$\Delta x_1 = q \cdot a_1 + p \cdot o_1$$

$$\underline{x_1 = x_a + \Delta x_1}$$



Položaj male točke bit će definiran svojim mjerenim relativnim koordinatama. Relativne koordinate male točke na okomici su apscise a_i , i ordinate o_i .

Male točke na okomici

$$(\delta y_2) = a_2 \cdot \sin \nu_a^b$$

$$(\delta y_2') = (o_1 + o_2) \cdot \sin(\nu_a^b + 90^\circ) = (o_1 + o_2) \cdot \cos \nu_a^b$$

$$\Delta y_1 = a_1 \cdot \sin \nu_a^b + (o_1 + o_2) \cdot \cos \nu_a^b$$

$$\Delta y_2 = p \cdot a_2 + q \cdot (o_1 + o_2)$$

$$\underline{y_2 = y_1 + \Delta y_2}$$

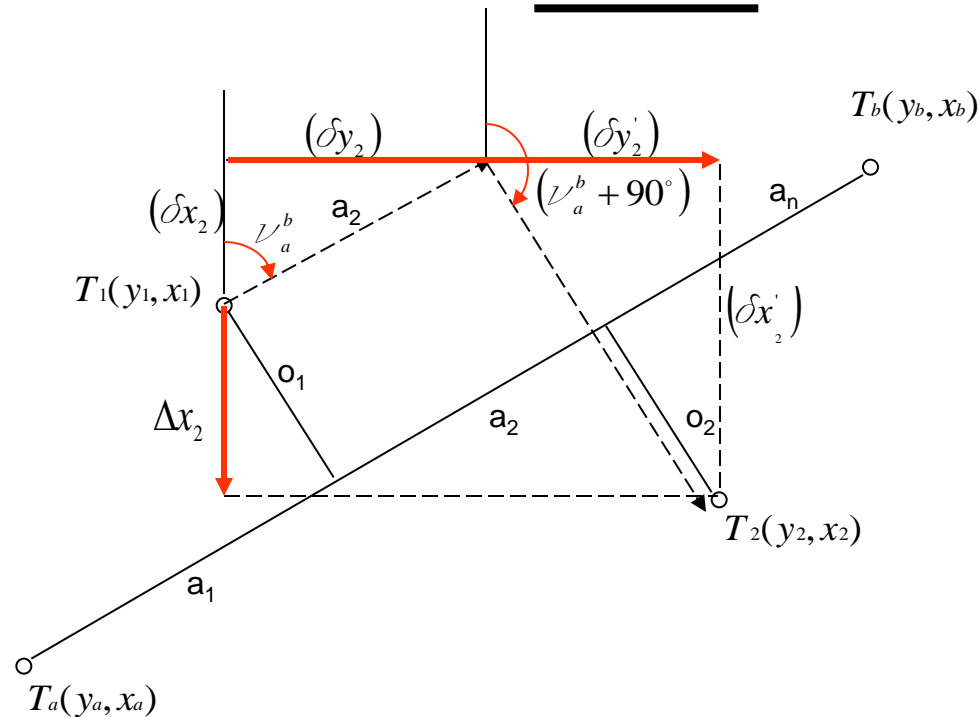
$$(\delta x_2) = a_2 \cdot \cos \nu_a^b$$

$$(\delta x_2') = (o_1 + o_2) \cdot \cos(90^\circ + \nu_a^b) = -(o_1 + o_2) \cdot \sin \nu_a^b$$

$$\Delta x_2 = a_2 \cdot \cos \nu_a^b - (o_1 + o_2) \cdot \sin \nu_a^b$$

$$\Delta x_2 = q \cdot a_2 - p \cdot (o_1 + o_2)$$

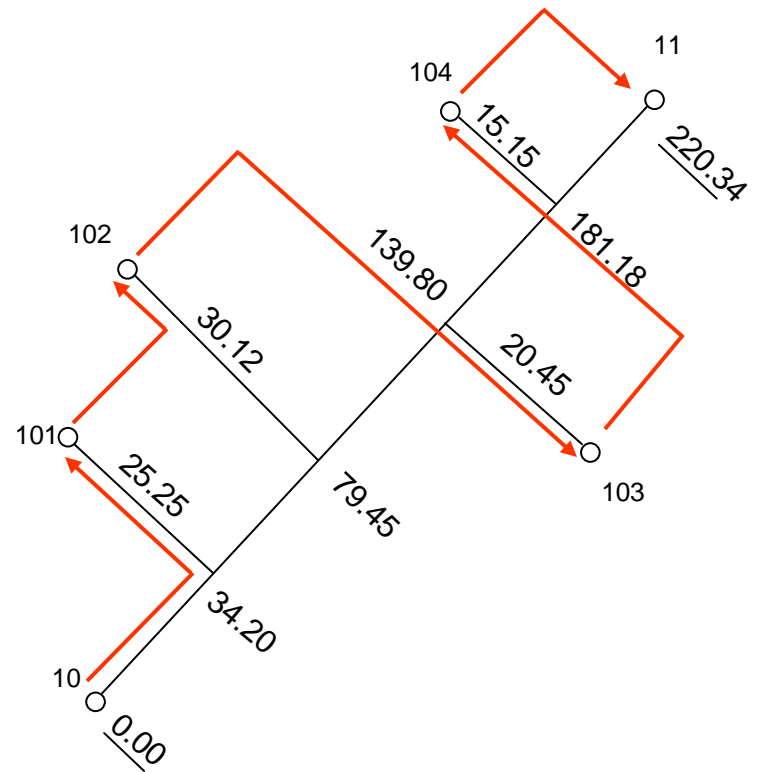
$$\underline{x_2 = x_1 + \Delta x_2}$$



Položaj male točke bit će definiran svojim mjerenim relativnim koordinatama. Relativne koordinate male točke na okomici su apscise a_i , i ordinate o_i .

Tr.obr.br.22.

$p = \frac{(y_b - y_a)}{[a]} \quad d = \sqrt{(y_b - y_a)^2 + (x_b - x_a)^2} \quad \Delta y = p \cdot a + q \cdot o \quad y_n = y_{n-1} + \Delta y$						
$q = \frac{(x_b - x_a)}{[a]} \quad f_d = d - [a] \quad \Delta x = q \cdot a - p \cdot o \quad x_n = x_{n-1} + \Delta x$						
$p = 0.91636$	a	$+o$	$-o$	y_n	x_n	Br. toč.
$q = 0.39970$				45123.54	34512.48	10
$p^2 = 0.83972$	34.20		25.25	21.25	36.81	101
				45144.79	34549.29	
$q^2 = 0.15976$	45.25		4.87	39.52	22.55	102
				45184.31	34571.84	
$1 \approx 0.99948$	60.35	50.57		75.51	-22.22	103
				45259.82	34549.62	
$(y_b - y_a)^2 = 40767.65$	41.38		35.60	23.69	49.16	104
				45283.51	34598.78	
$(x_b - x_a)^2 = 7756.32$	39.16	15.15		41.94	1.77	11
				45325.45	34600.55	
$d^2 = 48523.97$	220.34	65.72	65.72			
				201.91	88.07	
$d = 220.28$						
$[a] = 220.34$						
$f_d = -0.06$						
$\Delta. = \pm 0.10$						



Male točke na okomici - poligonski vlak

1. Računanje smjernog kuta ν_a^b
2. Računanje smjernog kuta $\nu_1 = \nu_a^b + \beta \pm 180^\circ$
3. Računanje koord.razlika nožišta točke T_1

$$\Delta y_1' = a_1 \cdot \sin \nu_a^b \quad \Delta x_1' = a_1 \cdot \cos \nu_a^b$$

4. Računanje koord. nožišta

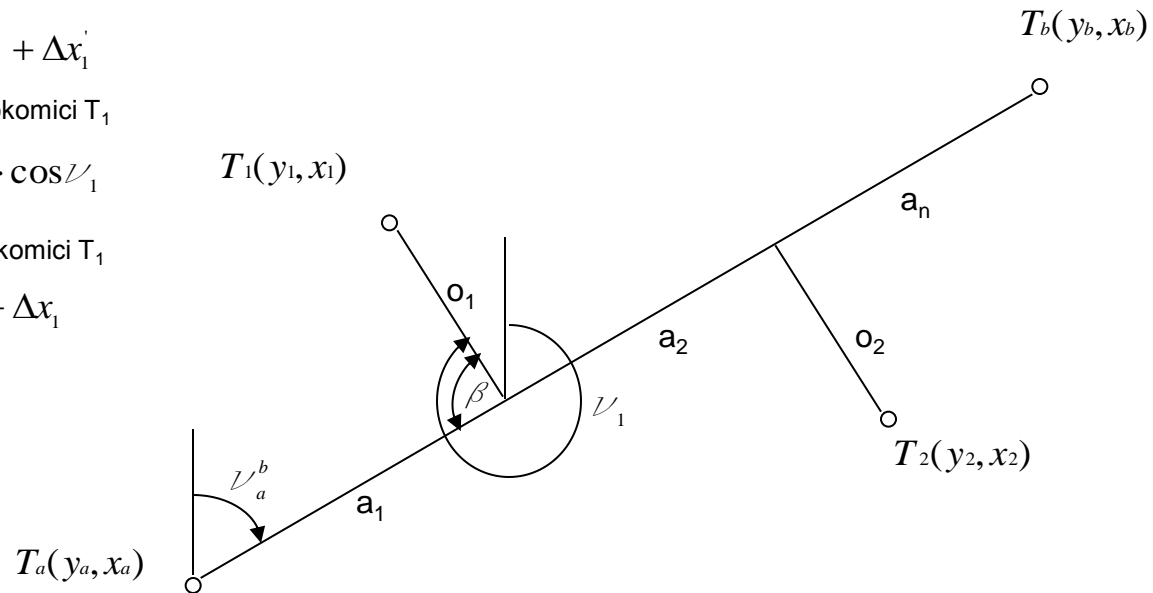
$$y_1' = y_a + \Delta y_1' \quad x_1' = x_a + \Delta x_1'$$

5. Računanje koord.razlika točke na okomici T_1

$$\Delta y_1 = o_1 \cdot \sin \nu_1 \quad \Delta x_1 = o_1 \cdot \cos \nu_1$$

6. Računanje koord. male točke na okomici T_1

$$y_1 = y_1' + \Delta y_1 \quad x_1 = x_1' + \Delta x_1$$



BR. POLIG.	PRELOMN I I VEZNI KUTOVI	SMJERNI KUTOVI	DUŽINE	$\Delta y = d \sin \nu$	$\Delta x = d \cos \nu$	$y_n = y_{n-1} + \Delta y$	$x_n = x_{n-1} + \Delta x$	BR. POLIG.
10						45123.54	34512.48	10
101a	90 00 00	66 26 03	34.20	31.35	13.67	31.35	13.67	101a
101	270 00 00	336 26 03	25.25	-10.10	23.14	-10.10	23.14	101
102a	90 00 00	66 26 03	45.25	-1 41.48	18.09	41.47	18.09	102a
102	270 00 00	336 26 03	4.87	-1.95	4.46	-1.95	4.46	102
103a	270 00 00	66 26 03	60.35	-1 55.32	-1 24.13	55.31	24.12	103a
103	90 00 00	156 26 03	50.57	-1 20.22	-46.35	20.21	-46.35	103
104a	90 00 00	66 26 03	41.38	-1 37.92	16.54	37.91	16.54	104a
104	270 00 00	336 26 03	35.60	-14.23	32.63	-14.23	32.63	104
11a	270 00 00	66 26 03	39.16	-1 35.89	15.66	35.88	15.66	11a
11	270 00 00	156 26 03	15.15	6.06	-13.89	6.06	-13.89	11
				201.96	88.08	45325.45	34600.55	11
		246 26 03		$f_y = -0.05$	$f_x = -0.01$	201.91	88.07	

